

# **Explaining Sequences of Actions in Multi-Agent Deep Reinforcement Learning Models**



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# Background

- This paper introduces a method to explain MADRL agents' behaviors by abstracting their actions into high-level strategies.
- Particularly, a spatio-temporal neural network model is applied to encode the agents' sequences of actions as memory episodes wherein an aggregating memory retrieval can generalize them into a concise abstract representation of collective strategies.
- To assess the effectiveness of our method, we applied it to explain the actions of QMIX MADRL agents playing a StarCraft Multi-agent Challenge (SMAC) video game.
- A user study on the perceived explainability of the extracted strategies indicates that our method can provide comprehensible explanations at various levels of granularity.

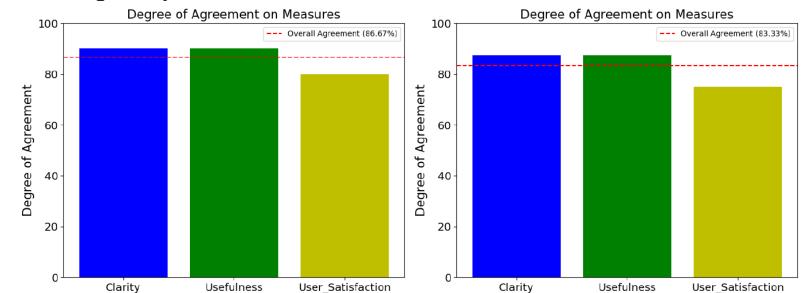
#### **KEYWORDS**

Multi Agent Deep Reinforcement Learning; Explainable Artificial Intelligence; Explainable Deep Reinforcement Learning.

#### **Approach and Methodology**

# **User Study**

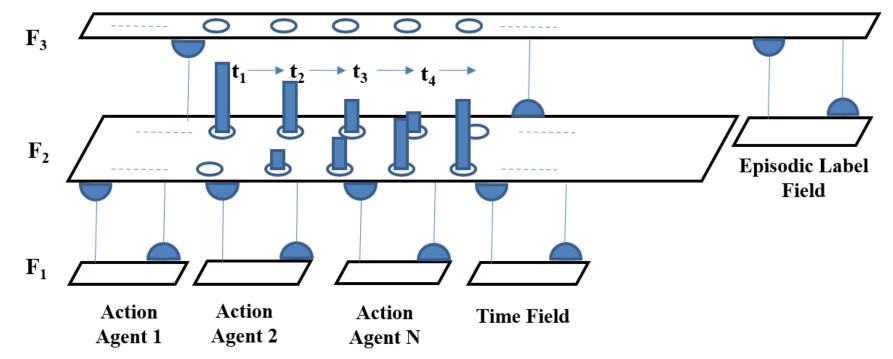
- A user study was conducted by using a method known as Inter-Rater Agreement Analysis [6] to examine the impact of explaining action sequences executed by multiple agents in terms of clarity, usefulness, and user satisfaction.
- The study utilized an online survey with a diverse participant group, evaluating unexplained and explained gameplay videos across five distinct games for SMAC's *4t* and *4t8sp* scenarios, with participants answering six questions per game and providing Likert scale ratings (1 to 5) to assess explanation quality.



 Our proposed framework for explaining opaque MADRL models consists of two main stages, outlined as follows.

**Step 1: Memory Encoding.** The learned behaviors of the MADRL agents, in terms of sequences of actions performed, are encoded using an episodic memory model, such as EM-ART [1, 2, 3], which learns the salient action patterns over time.

**Step 2: Abstracting the Learned Knowledge.** The generalized joint actions and sequences learned in the episodic memory models are extracted and further abstracted into high-level strategies for explanation.



**Figure 1:** The network architecture of the EM-ART 2 model for encoding sequences of actions performed by multiple agents over time.

- Action events' timestamps are encoded using complement coding in a time input field. This allows for applying an interval-based memory retrieval procedure to generalize agents' encoded actions and behavior patterns over selected time intervals into abstract sequential patterns.
- Subsequently, the abstracted sequences of action events undergo a two-stage process: selecting significant events and removing repeated events, resulting in shorter sequences of unique significant events.

#### (a) 4t Scenario

**Figure 2:** Degree of agreement among participants regarding clarity, usefulness and user satisfaction that are above the agreement rating threshold (>4).

(b) 4t8sp Scenario

- Respondents exhibited high levels of agreement on clarity, usefulness, and user satisfaction regarding explanations for actions in the *4t* scenario, with an overall agreement of 86.67%.
- In the study of the 4t8sp scenario, assessments revealed clear explanations with significant consensus on their importance, resulting in an overall agreement of 83.33%, slightly lower than the 4t scenario but still indicating substantial consensus among respondents.
- The results suggest that the explanations were overall well-received and effectively conveyed the sequences of actions by the agents.
- These findings thus support the effectiveness of the explanation system, even in complex scenarios like *4t8sp*.

### Conclusion

- This work introduces a methodology using the EM-ART 2 model to interpret sequences of actions by decentralized agents trained with the QMIX model.
- The methodology generalizes and abstracts action sequences using timebased retrieval and two episode abstraction algorithms, effectively explaining multi-agent team behavior.
- It is applicable not only to QMIX-trained MADRL agents but also adaptable to models trained by different algorithms, potentially expediting the learning process.
- Future research aims to incorporate contextual information for deeper insights into MADRL decision-making processes.

# Acknowledgement

## Experiments

- Using the SMAC [4] platform, the proposed method utilizes QMIX [5] for training and explains gameplay in scenarios 4t and 4t8sp, involving four siege tanks against enemy units and strategic point objectives.
- Table 1 presents a winning episode abstraction for the *4t8sp* scenario, with an abstraction factor of 60, summarizing agent actions into intervals for enhanced analysis.

**Table 1:** A winning episode for the *4t8sp* scenario derived with event abstraction over two (or more) agents and episode abstraction over time. Legend of actions: N, S, E, and W indicate move north, south, east, and west respectively;  $A_i$  indicates attack[enemy\_i]; and X indicates no\_op.

Time Interval	Action	Time Interval	Action
t1-t4	WN	t69-t72	$A_0$
t5-t8	S	t73-t76	$A_3$
t9-t16	E	t77-t84	XN
t17-t20	NE	t85-t88	XW
t21-t24	E	t89-t112	XN
t25-t28	Ν	t113-t132	XE
t29-t32	WN	t133-t140	XN
t33-t36	EN	t141-t148	XE
t37-t48	Ν	t149-t172	XS
t49-t52	NW	t173-t184	XE
t53-t56	Ν	t185-t192	XS
t57-t60	$A_1$	t193-t212	XE
t61-t68	$A_2$	t213-t254	XN

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